

Summer of Avionics Plan

Scope

Main goals

Design a system of tools to make a minimum viable Avdasi 2 Avionics model.

1. Research I2C pressure tapping + integration

- Tim's board

2. Basic cube configuration guide

2.1. Pymavlink

- How to connect to cube
- Links to relevant ardupilot docs

2.2. Wifi

- How to set it up
- How to connect to it

2.3. Rc

- How to configure channels
- How to pair with cube
- Have RC as main/wifi as backup

2.4. I2C & Lua cube guide

- Link ardupilot LUA documentation
- Guide to I2C wiring

3. Example code – minimum viable

3.1. Flap sensor example code

- Take adc from average sensor and store it
- Bit operations
- Send to gcs

3.2. Servo control example code

3.3. Ground station example code

- Connect to cube through Mavlink

3.4. Arm disarm example code

3.5. UI example code

- Make ugly
- Angle input for 1 control surface
- Connection status
- Arm disarm button

3.6. Cube mode switching example code

- Template could be any mode
 - Stabilize/Manual or Rc/Wifi
- 3.7. Pressure sensor example code
- 4. Flat board demonstration of everything**

Stretch goals

5. Mechanical demonstrations

- 5.1. Flap
- 5.2. Aileron/Rudder/Elevator
- 5.3. Flap sensor
- Potentiometer installation
- 5.4. Basic minimum working example for above
- 5.5. Excellent example for above
- 5.6. Pressure tap rib good example

6. Telemetry Processing examples

- 6.1. Find resource to make it easy

7. Servo mechanism calibration tool

- Mock mechanism test demonstrator (so you can test before the rest thing is built)

Schedule

Week	M	Tu	W	Th	F
12/5	Plan			1.	2.
19/5					3.1.-3.6.
26/5					4.
2/6	3.7.				
9/6					7.
16/6					
23/6					6. 8.